

The Mondshein Sequence

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Abstract

Canonical orderings [STOC'88, FOCS'92] have been used as a key tool in graph drawing, graph encoding and visibility representations for the last decades. We study a far-reaching generalization of canonical orderings to non-planar graphs that was published by Lee Mondshein in a PhD-thesis at M.I.T. as early as 1971.

Mondshein proposed to order the vertices of a graph in a sequence such that, for any i , the vertices from 1 to i induce essentially a 2-connected graph while the remaining vertices from $i + 1$ to n induce a connected graph. Mondshein's sequence generalizes canonical orderings and became later and independently known under the name *non-separating ear decomposition*. Currently, the best known algorithm for computing this sequence achieves a running time of $O(nm)$; the main open problem in Mondshein's and follow-up work is to improve this running time to a subquadratic time.

In this paper, we present the first algorithm that computes a Mondshein sequence in time and space $O(m)$, improving the previous best running time by a factor of n . In addition, we illustrate the impact of this result by deducing linear-time algorithms for several other problems, for which the previous best running times have been quadratic.

In particular, we show how to compute three independent spanning trees in a 3-connected graph in linear time, improving a result of Cheriyan and Maheshwari [J. Algorithms 9(4)]. Secondly, we improve the preprocessing time for the output-sensitive data structure by Di Battista, Tamassia and Vismara [Algorithmica 23(4)] that reports three internally disjoint paths between any given vertex pair from $O(n^2)$ to $O(m)$. Finally, we show how a very simple linear-time planarity test can be derived once a Mondshein sequence is computed.

1 Introduction

Canonical orderings are a fundamental tool used in graph drawing, graph encoding and visibility representations; we refer to [1] for a wealth of applications. For maximal planar graphs, canonical orderings were first introduced by de Fraysseix, Pach and Pollack [7, 8] in 1988. Kant then generalized canonical orderings to 3-connected planar graphs [15, 16]. A generalization to arbitrary planar graphs was given by Chiang, Lin and Lu [5].

Surprisingly, the concept of canonical orderings can be traced back much further, namely to a long-forgotten PhD-thesis at M.I.T. by Lee F. Mondshein [18] in 1971. In fact, Mondshein proposed a sequence that generalizes canonical orderings to non-planar graphs, hence making them applicable to arbitrary 3-connected graphs. Mondshein's sequence was, independently and in a different notation, found later by Cheriyan and Maheshwari [4] under the name *non-separating ear decompositions*.

Computationally, it is an intriguing question how fast a Mondshein sequence can be computed. Mondshein himself gave an involved algorithm with running time $O(m^2)$. Cheriyan showed that

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it is possible to achieve a running time of $O(nm)$ by using a theorem of Tutte that proves the existence of non-separating cycles in 3-connected graphs [22]. Both works (see [18, p. 1.2] and [4, p. 532]) state as main open problem, whether it is possible to compute a Mondschein sequence in subquadratic time.

We present the first algorithm that computes a Mondschein sequence in time and space $O(m)$, hence solving the above 40-year-old problem. The interest in such a computational result stems from the fact that 3-connected graphs play a crucial role in algorithmic graph theory. We illustrate this in five applications by giving linear-time (and hence optimal) algorithms for several problems. For three of them, the previous best running times have been quadratic.

In particular, we show how to compute three independent spanning trees in a 3-connected graph in linear time, improving a result of Cheriyan and Maheshwari [4]. Second, we improve the preprocessing time from $O(n^2)$ to $O(m)$ for a data structure by Di Battista, Tamassia and Vismara [9] that reports three internally disjoint paths in a 3-connected graph between any given vertex pair in time $O(\ell)$, where ℓ is the total length of these paths. Finally, we illustrate the usefulness of Mondschein's sequence by giving a very simple linear-time planarity test, once a Mondschein sequence is computed.

We start by giving an overview of Mondschein's work and its connection to canonical orderings and non-separating ear decompositions in Section 3. Section 4 sketches the main ideas for our linear-time algorithm that computes a Mondschein sequence. Section 5 covers five applications of this linear-time algorithm.

2 Preliminaries

We use standard graph-theoretic terminology and assume that all graphs are simple.

Definition 1 ([17, 25]). An *ear decomposition* of a 2-connected graph $G = (V, E)$ is a sequence (P_0, P_1, \dots, P_k) of subgraphs of G that partition E such that P_0 is a cycle and every P_i , $1 \leq i \leq k$, is a path that intersects $P_0 \cup \dots \cup P_{i-1}$ in exactly its endpoints. Each P_i is called an *ear*. An ear is *short* if it is an edge and *long* otherwise.

According to Whitney [25], every ear decomposition has exactly $m - n + 1$ ears. For any i , let $G_i = P_0 \cup \dots \cup P_i$ and $\bar{V}_i := V - V(G_i)$. We write \bar{G}_i to denote the graph induced by \bar{V}_i . We observe that \bar{G}_i does not necessarily contain all edges in $E - E(G_i)$; in particular, there may be short ears in $E - E(G_i)$ that have both of their endpoints in G_i .

For a path P and two vertices x and y in P , let $P[x, y]$ be the subpath in P from x to y . A path with endpoints v and w is called a *vw-path*. A vertex x in a *vw-path* P is an *inner vertex* of P if $x \notin \{v, w\}$. For convenience, every vertex in a cycle is an inner vertex of that cycle.

The set of inner vertices of an ear P is denoted as $inner(P)$. The inner vertex sets of the ears in an ear decomposition of G play a special role, as they partition $V(G)$. Every vertex of G is contained in exactly one long ear as inner vertex. This gives readily the following characterization of \bar{V}_i .

Observation 2. For every i , \bar{V}_i is the union of the inner vertices of all long ears P_j with $j > i$.

We will compare vertices and edges of G by their first occurrence in a fixed ear decomposition.

Definition 3. Let $D = (P_0, P_1, \dots, P_{m-n})$ be an ear decomposition of G . For an edge $e \in G$, let $birth_D(e)$ be the index i such that P_i contains e . For a vertex $v \in G$, let $birth_D(v)$ be the minimal i such that P_i contains v (thus, $P_{birth_D(v)}$ is the ear containing v as an inner vertex). Whenever D is clear from the context, we will omit D .

Clearly, for every vertex v , the ear $P_{\text{birth}(v)}$ is long, as it contains v as an inner vertex.

3 Generalizing Canonical Orderings

We give a compact rephrasing of canonical orderings in terms of non-separating ear decompositions. This will allow for an easier comparison of a canonical ordering and its generalization to non-planar graphs, as the latter is also based on ear decompositions. We assume that the input graphs are 3-connected and, when talking about canonical orderings, planar. It is well-known that maximal planar graphs, which were considered in [7], form a subclass of 3-connected graphs (apart from the triangle-graph).

Definition 4. An ear decomposition is *non-separating* if, for $0 \leq i \leq m - n$, every inner vertex of P_i has a neighbor in $\overline{G_i}$ unless $\overline{G_i} = \emptyset$.

The name *non-separating* refers to the following helpful property.

Lemma 5. *In a non-separating ear decomposition D , $\overline{G_i}$ is connected for every i .*

Proof. Let u be an inner vertex of the last long ear in D . If $\overline{G_i} = \emptyset$, the claim is true. Otherwise, consider any vertex x in $\overline{G_i}$. In order to show connectedness, we exhibit a path from x to u in $\overline{G_i}$. If x is an inner vertex of $P_{\text{birth}(u)}$, this path is just the path $P_{\text{birth}(u)}[x, u]$. Otherwise, $\text{birth}(x) < \text{birth}(u)$. Then x has a neighbor in $\overline{G_{\text{birth}(x)}}$, since D is non-separating, and, according to Observation 2, this neighbor is an inner vertex of some ear P_j with $j > \text{birth}(x)$. Applying induction on j gives the desired path to u . \square

A *plane graph* is a graph that is embedded into the plane. In particular, a plane graph has a fixed outer face. We define canonical orderings as special non-separating ear decompositions.

Definition 6 (canonical ordering). Let G be a 3-connected plane graph having the edges tr and ru in its outer face. A *canonical ordering* with respect to tr and ru is an ear decomposition D of G such that

1. $tr \in P_0$,
2. $P_{\text{birth}(u)}$ is the last long ear, contains u as its only inner vertex and does not contain ru , and
3. D is non-separating.

The original definition of canonical orderings by Kant [16] states several additional properties, all of which can be deduced from the ones given in Definition 6. E.g., it is easy to see for every i that the outer face C_i of G_i forms a cycle containing tr .

The fact that D is non-separating plays a key role for both canonical orderings and their generalization to non-planar graphs. E.g., for canonical orderings, Lemma 5 implies that the plane graph G can be constructed from P_0 by successively inserting the ears of D to only one dedicated face of the current embedding, a routine that is heavily applied in graph drawing and embedding problems.

Our definition of canonical orderings uses planarity only in one place: $tr \cup ru$ is assumed to be part of the outer face of G . Note that the essential part of this assumption is that $tr \cup ru$ is part of some face of G , as we can always choose an embedding for G having this face as outer face. By dropping this assumption, our definition of canonical orderings can be readily generalized to non-planar graphs: We merely require tr and ru to be edges in the graph.

This is in fact equivalent to the definition Mondschein used 1971 to define a *(2,1)-sequence* [18, Def. 2.2.1], but which he gave in the notation of a special vertex ordering. This vertex ordering

actually refines the partial order $inner(P_0), \dots, inner(P_{m-n})$ by enforcing an order on the inner vertices of each path according to their occurrence on that path (in any direction). The statement that canonical orderings can be extended to non-planar graphs can also be found in [10, p.113], however, no further explanation is given. For conciseness, we will stick to the following short ear-based definition, which is similar to the one given in [4] but does not need additional degree-constraints.

Definition 7 ([18, 4]). Let G be a graph with an edge ru . A *Mondshein sequence avoiding ru* (see Figure 3a) is an ear decomposition D of G such that

1. $r \in P_0$,
2. $P_{birth(u)}$ is the last long ear, contains u as its only inner vertex and does not contain ru , and
3. D is non-separating.

An ear decomposition D that satisfies Conditions 1 and 2 is said to *avoid ru* . Put simply, this forces ru to be “added last” in D , i.e., strictly after the last long ear $P_{birth(u)}$ has been added. Note that Definition 7 implies $u \notin P_0$, as $P_{birth(u)}$ contains only one inner vertex. As a direct consequence of this and the fact that D is non-separating, G must have minimum degree 3 in order to have a Mondshein sequence. Mondshein proved that every 3-connected graph has a Mondshein sequence. In fact, also the converse is true.

Theorem 8 (compare also [4, 26]). *Let $ru \in E(G)$. Then G is 3-connected if and only if r is not contained in a 2-separator and G has a Mondshein sequence avoiding ru .*

We state two additional facts about Mondshein sequences. Since we replaced the assumption that $tr \cup ru$ is in the outer face of G with the very small assumption that ru is an edge of G (which does not assume anything about t at all), it is natural to ask how we can extract t (and thus, a canonical ordering) from a Mondshein sequence when G is plane. We choose t as any neighbor of r in P_0 . Since P_0 is non-separating and the non-separating cycles of a 3-connected plane graph are precisely its faces [22], this satisfies Definition 6 and leads to the following observation.

Observation 9. *Let D be a Mondshein sequence avoiding ru of a planar graph G and let t be a neighbor of r in P_0 . Then D is a canonical ordering of the planar embedding of G whose outer face contains $tr \cup ru$.*

Once having a Mondshein sequence, one can aim for a slightly stronger structure. A *chord* of an ear P_i is an edge in G that joins two non-adjacent vertices of P_i . Let a Mondshein sequence be *induced* if P_0 is induced in G and every ear $P_i \neq P_0$ has no chord in G , except possibly the chord joining the endpoints of P_i . The following lemma shows that we can always expect induced Mondshein sequences.

Lemma 10. *Every Mondshein sequence can be transformed to an induced Mondshein sequence in linear time.*

4 Computing a Mondshein Sequence

Mondshein gave an involved algorithm [18] that computes his sequence in time $O(m^2)$. Independently, Cheriyan and Maheshwari gave an algorithm that runs in time $O(nm)$ and which is based on a theorem of Tutte. At the heart of our linear-time algorithm is the following classical construction sequence for 3-connected graphs due to Barnette and Grünbaum [2] and Tutte [23, Thms. 12.64 and 12.65].

Definition 11. The following operations on simple graphs are *BG-operations* (see Figure 1).

- (a) *vertex-vertex-addition*: Add an edge between two distinct non-adjacent vertices
- (b) *edge-vertex-addition*: Subdivide an edge ab , $a \neq b$, by a vertex v and add the edge vw for a vertex $w \notin \{a, b\}$
- (c) *edge-edge-addition*: Subdivide two distinct edges by vertices v and w , respectively, and add the edge vw

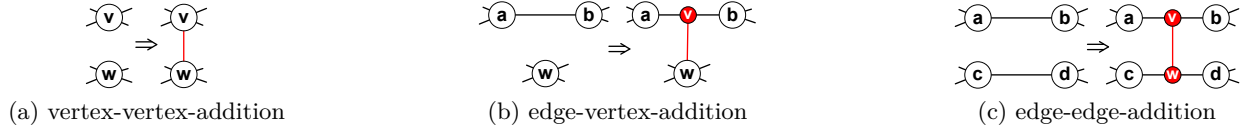


Figure 1: BG-operations

Theorem 12 ([2, 23]). *A graph is 3-connected if and only if it can be constructed from K_4 using BG-operations.*

Hence, applying an BG-operation on a 3-connected graphs preserves it to be simple and 3-connected. Let a *BG-sequence* of a 3-connected graph G be a sequence of BG-operations that constructs G from K_4 . It has been shown that such a BG-sequence can be computed efficiently.

Theorem 13 ([19, Thms. 6.(2) and 52]). *A BG-sequence of a 3-connected graph can be computed in time $O(m)$.*

The outline of our algorithm is as follows. We start with a Mondshein sequence of K_4 , which is easily obtained, and compute a BG-sequence of our 3-connected input graph by using Theorem 13. The crucial part is now a careful analysis that a Mondshein sequence of a 3-connected graph G can be modified to one of G' , where G' is obtained from G by applying a BG-operation.

This last step is the main technical contribution of this paper and depends on the various positions in the sequence in which the vertices and edges that are involved in the BG-operation can occur. We will prove that there is always a modification that is local in the sense that the only long ears that are modified are the ones containing a vertex that is involved in the BG-operation.

Lemma 14 (Path Replacement Lemma). *Let G be a 3-connected graph with an edge ru . Let $D = (P_0, P_1, \dots, P_{m-n})$ be a Mondshein sequence avoiding ru of G . Let G' be obtained from G by applying a single BG-operation Γ and let ru' be the edge of G' corresponding to ru . Then a Mondshein sequence D' of G' avoiding ru' can be computed from D using only constantly many (amortized) constant-time modifications.*

However, the complete description of these modifications goes beyond the scope of this extended abstract. We will therefore state precise modifications only for the very first cases of vertex-vertex- and edge-vertex-additions and omit everything else.

We need some notation for describing the modifications. Let vw be the edge that was added by Γ such that, if applicable, v subdivides $ab \in E(G)$ and w subdivides $cd \in E(G)$. Then the edge ru' of G' that *corresponds* to ru in G is either ru , rv or rw . Whenever we consider the edge ab or cd , e.g. in a statement about $birth(ab)$, we assume that Γ subdivides ab , respectively, cd . W.l.o.g., we further assume that $birth(a) \leq birth(b)$, $birth(c) \leq birth(d)$ and $birth(d) \leq birth(b)$. If not stated otherwise, the *birth*-operator refers always to D in this section. Let $S \subseteq \{av, vb, vw, cw, wd\}$ be the set of new edges in G' .

We state the detailed replacement scheme that plays a key-role in proving the above Path Replacement Lemma.

Lemma 15. *There is a Mondshein sequence $D' = (P'_0, P'_1, \dots, P'_{m-n+1})$ of G' avoiding ru (respectively, rv or rw if Γ subdivides ru) that can be obtained from D by performing the following four modifications:*

- M1) replacing the long ear $P_{\text{birth}(b)}$ with $1 \leq i \leq 3$ consecutive long ears P'_{b_1}, P'_{b_2} and P'_{b_3} , each of which consists of edges in $P_{\text{birth}(b)} \cup S$ (for notational convenience, we assume that all three ears exist such that $P'_{b_j} := P'_{b_i}$ for every $j > i$)
- M2) if $P_{\text{birth}(cd)}$ is long and $\text{birth}(d) < \text{birth}(b)$, replacing $P_{\text{birth}(cd)}$ with the long ear $P'_{c wd}$ that is obtained from $P_{\text{birth}(cd)}$ by subdividing cd with w (in particular, $\text{birth}(cd) = \text{birth}(d) < \text{birth}(b)$ in this case)
- M3) if $P_{\text{birth}(ab)}$ is short, deleting or replacing $P_{\text{birth}(ab)}$ with an edge in $\{va, vb, vw\}$; if $P_{\text{birth}(cd)}$ is short, deleting or replacing $P_{\text{birth}(cd)}$ with an edge in $\{wc, wd\}$
- M4) possibly adding vw as new last ear.

In particular, D' can be constructed from D as follows (Figure 2 determines the new ears $P'_{b_1} - P'_{b_3}$ in M1).

(1) Γ is a vertex-vertex-addition

Obtain D' from D by adding the new ear vw at the end.

(2) Γ is an edge-vertex-addition

(a) $\text{birth}(b) = \text{birth}(ab)$

Let a' and b' be the endpoints of $P_{\text{birth}(b)}$ such that a' is closer to a than to b on $P_{\text{birth}(b)}$ (a' may be a , but $b' \neq b$).

(i) $w \notin G_{\text{birth}(b)}$

$\triangleright \text{birth}(w) > \text{birth}(b)$

Obtain D' from D by subdividing $ab \subseteq P_{\text{birth}(b)}$ with v and adding the new ear vw at the end.

(ii) $w \in G_{\text{birth}(b)} - P_{\text{birth}(b)}$

$\triangleright \text{birth}(w) < \text{birth}(b)$ and $w \notin \{a', b'\}$

Let Z be the path obtained from $P_{\text{birth}(b)}$ by replacing ab with $av \cup vb$. Let Z_1 be the $a'w$ -path in $Z \cup vw$. Obtain D' from D by replacing $P_{\text{birth}(b)}$ with the two ears Z_1 and $Z[v, b']$ in that order.

(iii) $w \in P_{\text{birth}(b)}$

$\triangleright \text{birth}(w) = \text{birth}(b)$ or $w \in \{a', b'\}$

Let Z be obtained from $P_{\text{birth}(b)}$ by replacing ab with $av \cup vb$. Let Z_2 be the vw -path in Z (if $\text{birth}(b) = 0$, Z is a cycle and there are two vw -paths; we then choose one that does not contain r as an inner vertex). Let Z_1 be obtained from Z by replacing Z_2 with the edge vw . Obtain D' from D by replacing $P_{\text{birth}(b)}$ with the two ears Z_1 and Z_2 in that order.

We omit a concise proof of the correctness of Lemma 15 and, thus, of the Path Replacement Lemma 14. Using a suitable data structure, Lemma 14 can be applied iteratively for each operation in a BG-sequence in amortized constant time, giving a linear-time algorithm for constructing a Mondshein sequence. We conclude the following theorem.

Theorem 16. *Given an edge ru of a 3-connected graph G , a Mondshein sequence D of G avoiding ru can be computed in time $O(m)$.*

We now discuss five applications where Theorem 16 leads immediately to linear-time solutions. For three of these problems only quadratic algorithms have been known.

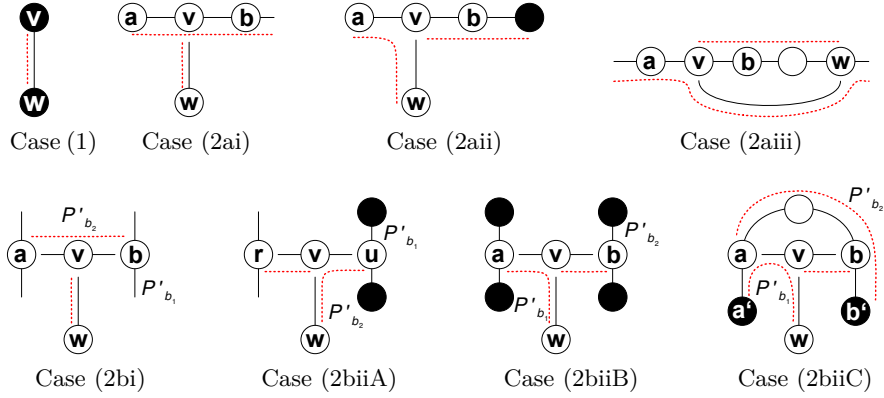


Figure 2: Cases (1) and first subcases of (2) of Lemma 15. Black vertices are endpoints of ears that are contained in $G_{birth(b)}$. The dashed paths depict (parts of) the ears in D' .

5 Applications

Application 1: Independent Spanning Trees

Let k spanning trees of a graph be *independent* if they all have the same root vertex r and, for every vertex $x \neq r$, the paths from r to x in the k spanning trees are *internally disjoint* (i.e., vertex-disjoint except for their endpoints). The following conjecture from 1988 due to Itai and Rodeh [14] has received considerable attention in graph theory throughout the past decades.

Conjecture (Independent Spanning Tree Conjecture [14]). Every k -connected graph contains k independent spanning trees.

The conjecture has been proven for $k \leq 2$ [14], $k = 3$ [4, 26] and $k = 4$ [6], with running times $O(m)$, $O(n^2)$ and $O(n^3)$, respectively, for computing the corresponding independent spanning trees. For $k \geq 5$, the conjecture is open. For planar graphs, the conjecture has been proven by Huck [13].

We show how to compute three independent spanning trees in linear time, using an idea of [4]. This improves the previous best running time by a factor of n . It may seem tempting to compute the spanning trees directly and without using a Mondschein sequence, e.g. by local replacements in an induction over BG-operations or inverse contractions. However, without additional structure it can be proven that this is bound to fail.

Compute a Mondschein sequence avoiding ru , as described in Theorem 16. Choose r as the common root vertex of the three spanning trees and let $x \neq r$ be an arbitrary vertex.

First, we show how to obtain two internally disjoint paths from x to r that are both contained in the subgraph $G_{birth(x)}$. An *st-numbering* π is an ordering $v_1 < \dots < v_n$ of the vertices of a graph such that $s = v_1$, $t = v_n$, and every other vertex has both a higher-numbered and a lower-numbered neighbor. Let π be *consistent* to a Mondschein sequence if π is an *st-numbering* for every graph G_i , $0 \leq i \leq m - n$. Let $t \neq u$ be a neighbor of r in P_0 . A consistent *rt-numbering* π can be easily computed in linear time [3]. According to π , we can start with x and iteratively traverse to a higher-numbered and lower-numbered neighbor, respectively, without leaving $G_{birth(x)}$. This gives two internally disjoint paths from x to r and t ; the path to t is then extended to the desired path ending at r by appending the edge tr . The traversed edges of this procedure for every $x \neq r$ give the first two independent spanning trees T_1 and T_2 .

We construct the third independent spanning tree. Since a Mondschein sequence is non-separating, we can start with any vertex $x \neq r$, traverse to a neighbor in $\overline{G_{birth(x)}}$ and iterate this procedure

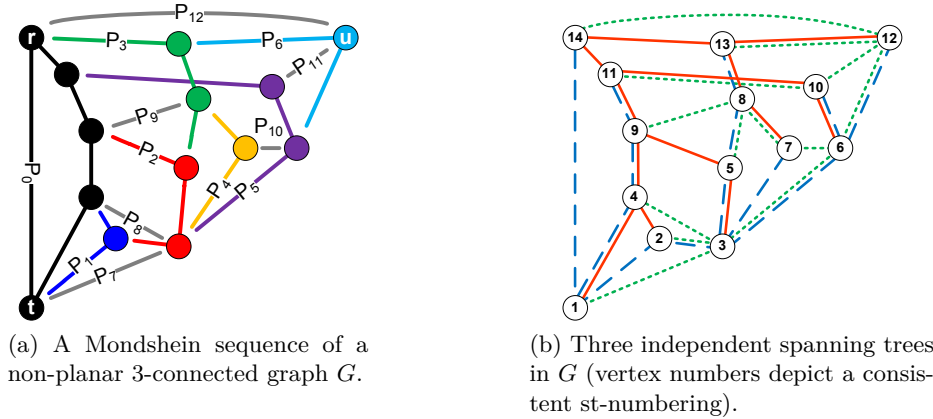


Figure 3

until we end at u . The traversed edges of this procedure for every $x \neq r$ form a tree that is rooted at u and that can be extended to a spanning tree T_3 that is rooted at r by adding the edge ur . T_3 is independent from T_1 and T_2 , as, for every $x \neq r$, the path from x to u intersects $G_{birth(x)}$ only in x .

Application 2: Output-Sensitive Reporting of Disjoint Paths

Given two vertices x and y of an arbitrary graph, a k -path query reports k internally disjoint paths between x and y or outputs that these do not exist. Di Battista, Tamassia and Vismara [9] give data structures that answer k -path queries for $k \leq 3$. A key feature of these data structures is that every k -path query has an *output-sensitive* running time, i.e., a running time of $O(\ell)$ if the total length of the reported paths is ℓ (and running time $O(1)$ if the paths do not exist). The preprocessing time of these data structures is $O(m)$ for $k \leq 2$, but $O(n^2)$ for $k = 3$.

For $k = 3$, Di Battista et al. show how the input graph can be restricted to be 3-connected using a standard decomposition. For every 3-connected graph we can compute a Mondsheim sequence, which allows us to compute three independent spanning trees T_1 – T_3 in a linear preprocessing time, as shown in Application 1. If x or y is the root r of T_1 – T_3 , this gives a straight-forward output-sensitive data structure that answers 3-path queries: we just store T_1 – T_3 and extract one path from each tree per query.

In order to extend these queries to k -path queries between arbitrary vertices x and y , [9] gives a case distinction that shows that the desired paths can be found efficiently in the union of the six paths in T_1 – T_3 that join x with r and y with r . This case distinction can be used for the desired output-sensitive reporting in time $O(\ell)$ without changing the preprocessing. We conclude that the preprocessing time of $O(n^2)$ for allowing k -path queries with $k \leq 3$ in arbitrary graphs can be improved to $O(n + m)$.

Application 3: Planarity Testing

We give a conceptually very simple planarity test based on Mondsheim’s sequence for any 3-connected graph G in time $O(n)$.

The 3-connectivity requirement is not really crucial, as the planarity of G can be reduced to the planarity of all 3-connected components of G , which in turn are computed as a side-product for the BG-sequence in Theorem 13; alternatively, one can use standard algorithms [12, 11] for reducing G to be 3-connected. We compute an induced Mondsheim sequence D avoiding an arbitrary edge

ru in time $O(n)$. Let t be a neighbor of r in P_0 .

We start with a planar embedding M_0 of P_0 and assume with Observation 9 w.l.o.g. that the last vertex u will be embedded in the outer face. We will first ignore short ears. Step by step, we attempt to augment M_i with the next long ear P_j in D in order to construct a planar embedding M_j of G_j .

Once the current embedding M_i contains u , we have added all the vertices of G and are done. Otherwise, u is contained in $\overline{G_i}$, according to Definition 6.2. Then $\overline{G_i}$ contains a path from each inner vertex of P_j to u , according to Lemma 5. Since u is contained in the outer face of the final embedding, adding the long ear P_j to M_i can preserve planarity only when it is embedded into the outer face f of M_i . Thus, we only have to check that both endpoints of P_j are contained in f (this is easy to test by maintaining the vertices of the current outer face). If yes, we embed P_j into f . Otherwise, we output “not planar”; if desired, a Kuratowski-subdivision can then be extracted in linear time.

Until now we ignored short ears, but have already constructed a planar embedding M' of a spanning subgraph of G . In order to test whether the addition of the short ears to M' can make the embedding non-planar, we pass through the construction of M' once more, this time adding short ears. Whenever a long ear P_j is embedded, we test whether all short ears that join a vertex of $inner(P_j)$ with a vertex of G_{j-1} can be embedded while preserving a planar embedding. Note that if D is a canonical ordering of M , G_{j-1} must be 2-connected and the outer face of G_{j-1} must be a cycle, according to [21, Corollary 1.3]. The last fact allows for an easy test whether adding the short ears preserves a planar embedding.

Application 5 (Bonus Application): The *3-Partitioning* Problem

At the time of submission, the author was pointed to the following problem. Given vertices v_1, \dots, v_k of a graph G and natural numbers n_1, \dots, n_k with $n_1 + \dots + n_k = n$, find a partition of V into sets V_1, \dots, V_k with $v_i \in V_i$ and $|V_i| = n_i$ for every i such that every set V_i induces a connected graph in G .

For general graphs G , this problem is NP-hard even for $k = 2$. However, for 3-connected graphs, the 3-partitioning problem can be solved in linear time if the input graph is *planar*. As suggested in [24], this problem (as well as a related extension) can be solved directly, once a non-separating ear decomposition has been computed. For planar graphs, we can thus use the (well-established) canonical ordering instead, which simplifies previous algorithms considerably.

More importantly, the fastest algorithm for the 3-partitioning problem in arbitrary 3-connected graphs runs in time $O(n^2)$ [20]. Combining a Mondshein sequence with a simple assignment of the vertices on ears to V_1, V_2 and V_3 (as shown in [24]) gives the first $O(m)$ algorithm for this problem.

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