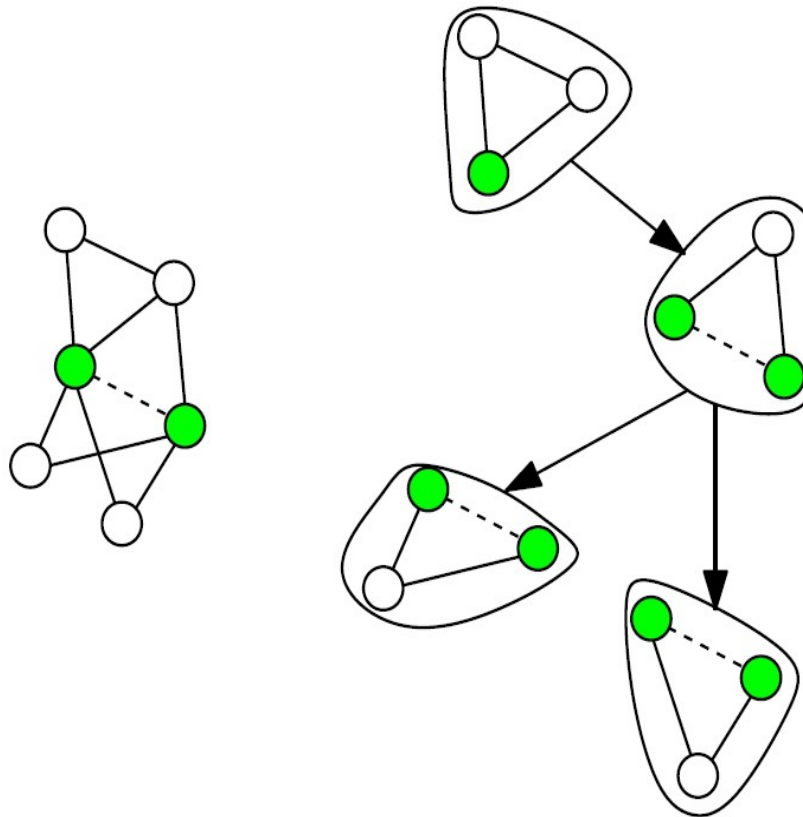


# Minimum Cycle Bases in Partial 2-Trees



Carola Doerr

G. Ramakrishna

Jens M. Schmidt

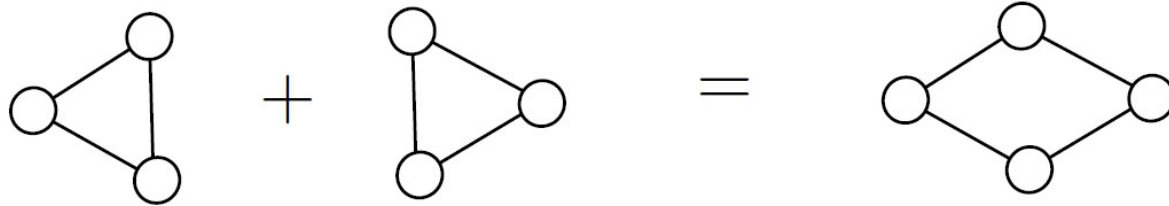
# Minimum Cycle Basis (MCB)

- $G$  = graph with non-negative weights

# Minimum Cycle Basis (MCB)

- $G$  = graph with non-negative weights
- **cycle basis** = minimum-cardinality set of cycles that can generate every cycle in  $G$

$$C_1 + C_2 := E(C_1) \Delta E(C_2)$$

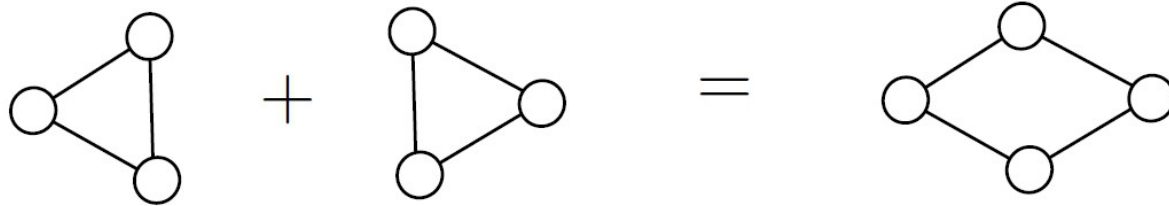


# Minimum Cycle Basis (MCB)

- $G$  = graph with non-negative weights
- **cycle basis** = minimum-cardinality set of cycles that can generate every cycle in  $G$

$m-n+1$

$$C_1 + C_2 := E(C_1) \Delta E(C_2)$$

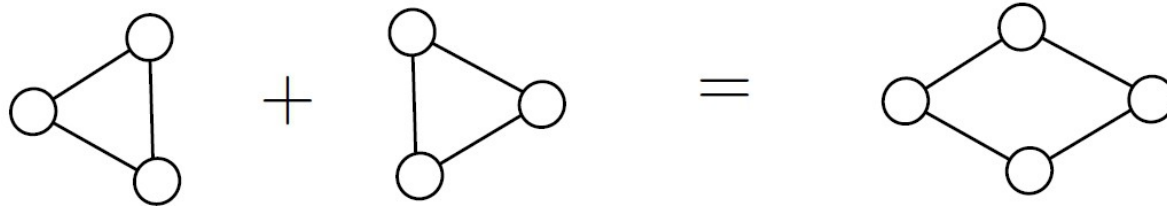


# Minimum Cycle Basis (MCB)

- $G$  = graph with non-negative weights
- **cycle basis** = minimum-cardinality set of cycles that can generate every cycle in  $G$

$m-n+1$

$$C_1 + C_2 := E(C_1) \Delta E(C_2)$$

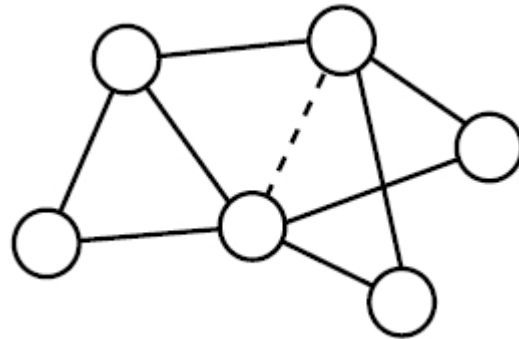


- **minimum cycle basis** = **minimize** sum of edge-weights



# Partial 2-Trees

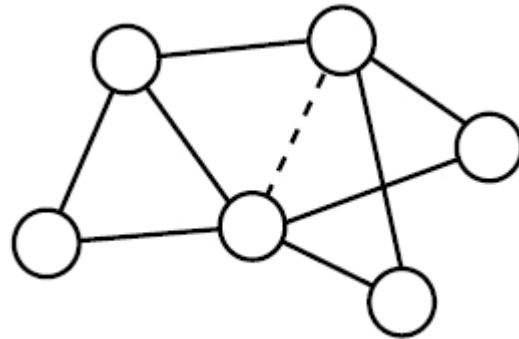
- **2-trees:**
  - Start with a triangle
  - Add iteratively new vertex that is adjacent to a  $K_2$



- **partial 2-trees** = subgraphs of **2-trees**

# Partial 2-Trees

- **2-trees:**
  - Start with a triangle
  - Add iteratively new vertex that is adjacent to a  $K_2$



- **partial 2-trees** = subgraphs of **2-trees**
- outerplanar graphs  $\subset$  **partial 2-trees**



# Recent Work

- For general graphs:
  - Deterministic:  $O(m^2n / \log n)$  [Amaldi-Iuliano-Rizzi '10]
  - Monte-Carlo:  $O(m^\omega)$  [“-Jurkiewicz-Mehlhorn '09]

# Recent Work

	[LL 2010]	[Our Result]	[BSW 2010]
	Outerplanar	Partial 2-trees	Planar
Preprocessing time	$O(n)$	$O(n)$	$O(n \log^5 n)$
Space required	$O(n)$	$O(n)$	$O(n \log n)$
Reporting time	$size(MCB)$	$size(MCB)$	$size(MCB)$

# Recent Work

	[LL 2010] Outerplanar	[Our Result] Partial 2-trees	[BSW 2010] Planar
Preprocessing time	$O(n)$	$O(n)$	$O(n \log^5 n)$
Space required	$O(n)$	$O(n)$	$O(n \log n)$
Reporting time	$size(MCB)$	$size(MCB)$	$size(MCB)$

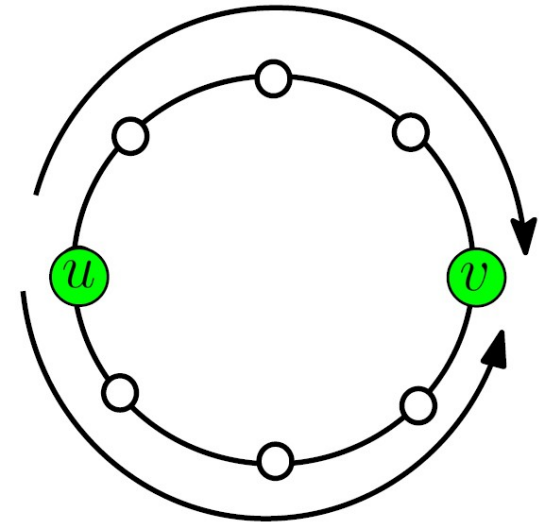
Can be big:  $\Omega(n^2)$

# Short Cycles

- Assumption:  
Unique shortest paths, otherwise [Hartvigsen-Mardon '94]

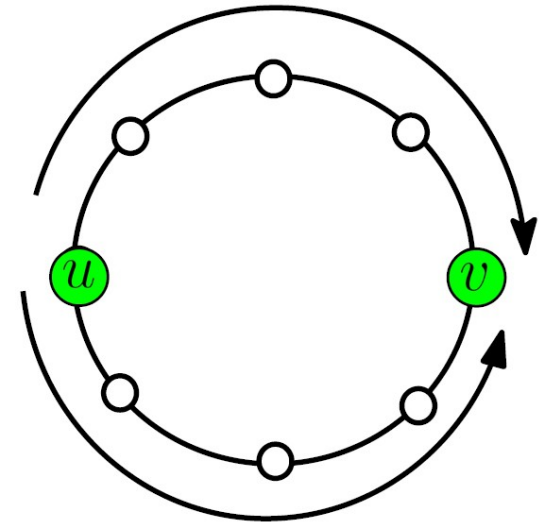
# Short Cycles

- Assumption:  
Unique shortest paths, otherwise [Hartvigsen-Mardon '94]
- $sp(u,v)$  = shortest path between  $u$  and  $v$
- Cycle  $C$  is **short** if for all  $u,v$  in  $C$ ,  $sp(u,v) \subseteq C$



# Short Cycles

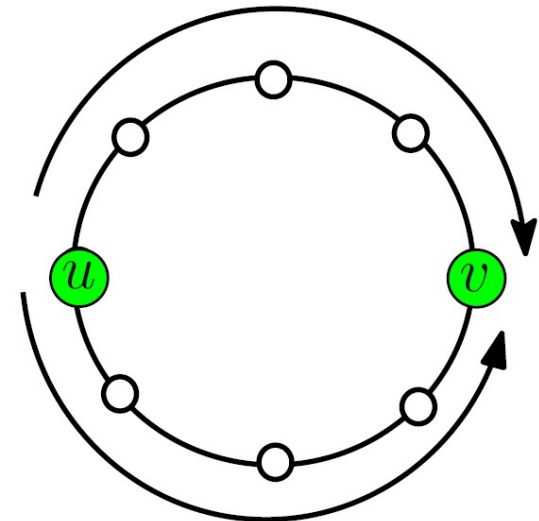
- Assumption:  
**Unique** shortest paths, otherwise [Hartvigsen-Mardon '94]
- $sp(u,v)$  = shortest path between  $u$  and  $v$
- Cycle  $C$  is **short** if for all  $u,v$  in  $C$ ,  $sp(u,v) \subseteq C$



- $SC$  = set of all short cycles

# Short Cycles

- Assumption:  
**Unique** shortest paths, otherwise [Hartvigsen-Mardon '94]
- $sp(u,v)$  = shortest path between  $u$  and  $v$
- Cycle  $C$  is **short** if for all  $u,v$  in  $C$ ,  $sp(u,v) \subseteq C$

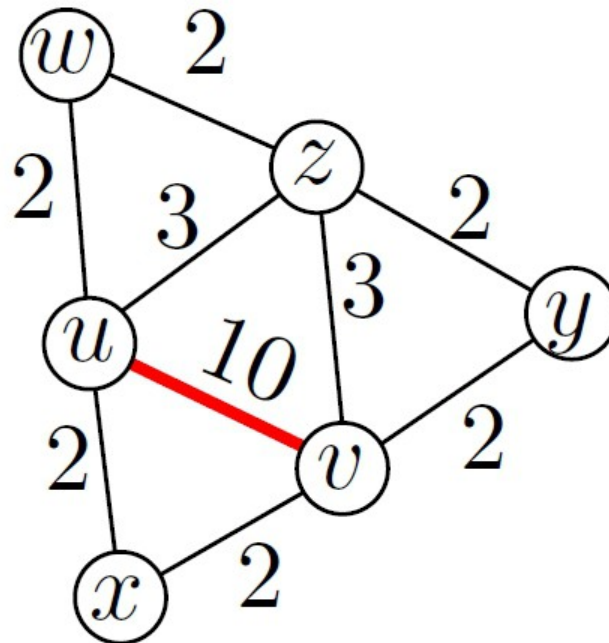


- $SC$  = set of all short cycles

Thm [N.+Ramakrishna '12]:  $MCB = SC$  for partial 2-trees

# Tight Edges

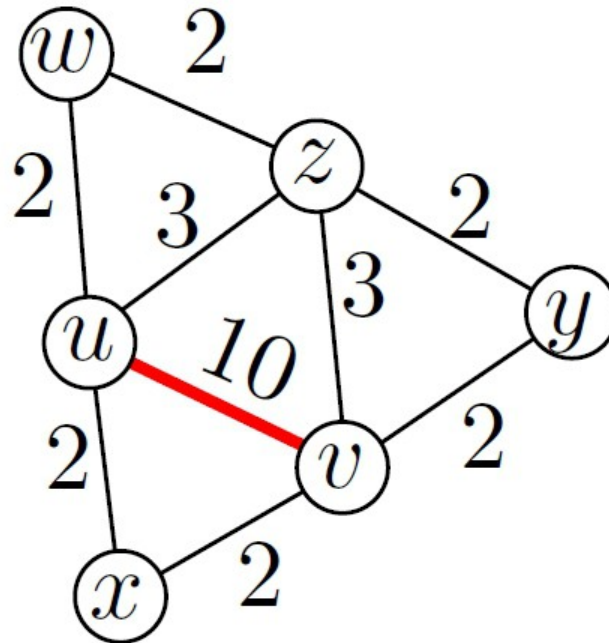
- Edge  $(u,v)$  **tight** if  $sp(u,v)=(u,v)$ , otherwise **loose**
- Every **loose** edge appears in exactly one SC





# Tight Edges

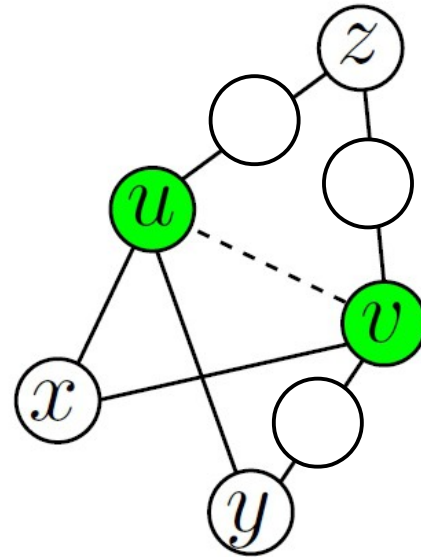
- Edge  $(u,v)$  **tight** if  $sp(u,v)=(u,v)$ , otherwise **loose**
- Every **loose** edge appears in exactly one SC



- Precompute these cycles  $\Rightarrow$   $G$  contains only **tight** edges

# Decomposition

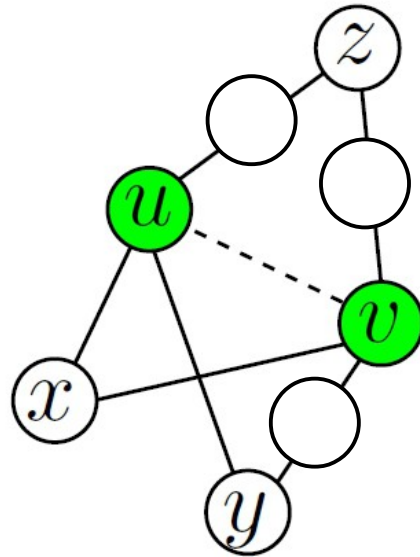
- If partial 2-tree has no  $K_{2,3}$ -subdivision  $\Rightarrow$  outerplanar!



- Decompose  $G$  along  $K_{2,3}$ -subdivisions into outerplanar graphs  $G_1, \dots, G_r$

# Decomposition

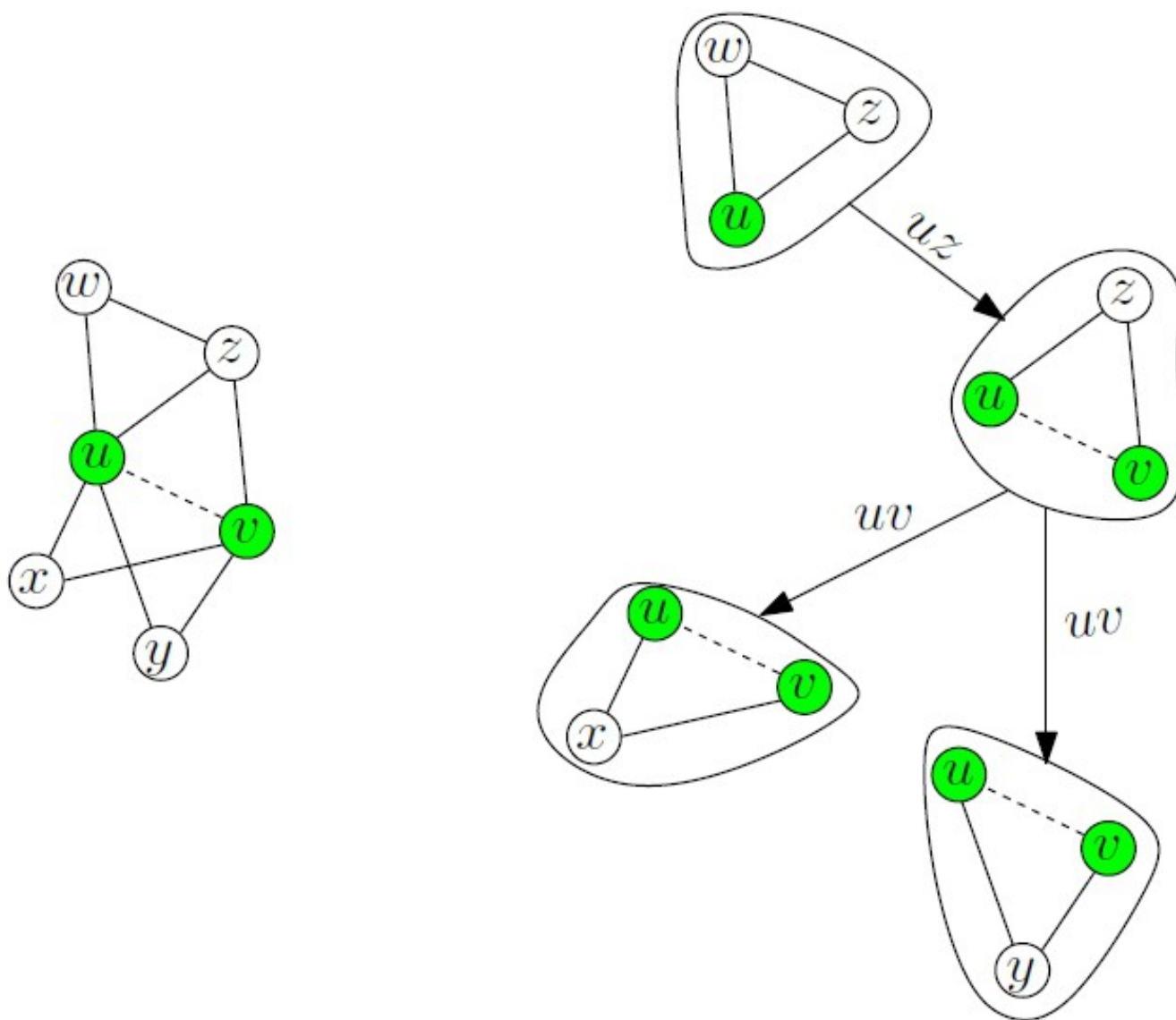
- If partial 2-tree has no  $K_{2,3}$ -subdivision  $\Rightarrow$  outerplanar!



- Decompose  $G$  along  $K_{2,3}$ -subdivisions into outerplanar graphs  $G_1, \dots, G_r$

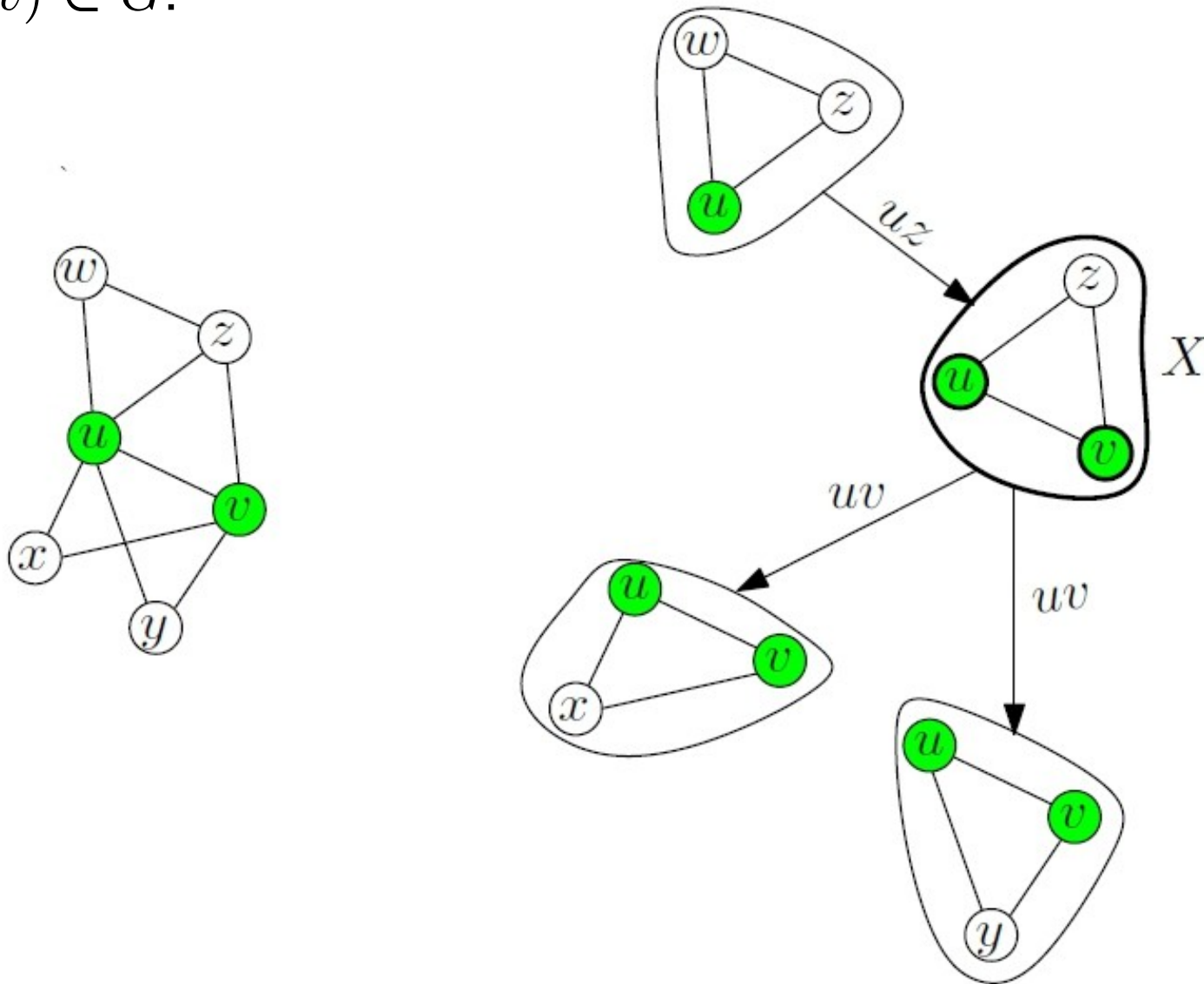
Thm [N.+Ramakrishna '12]:  $SC(G) = SC(G_1) \cup \dots \cup SC(G_r)$

# Decomposition



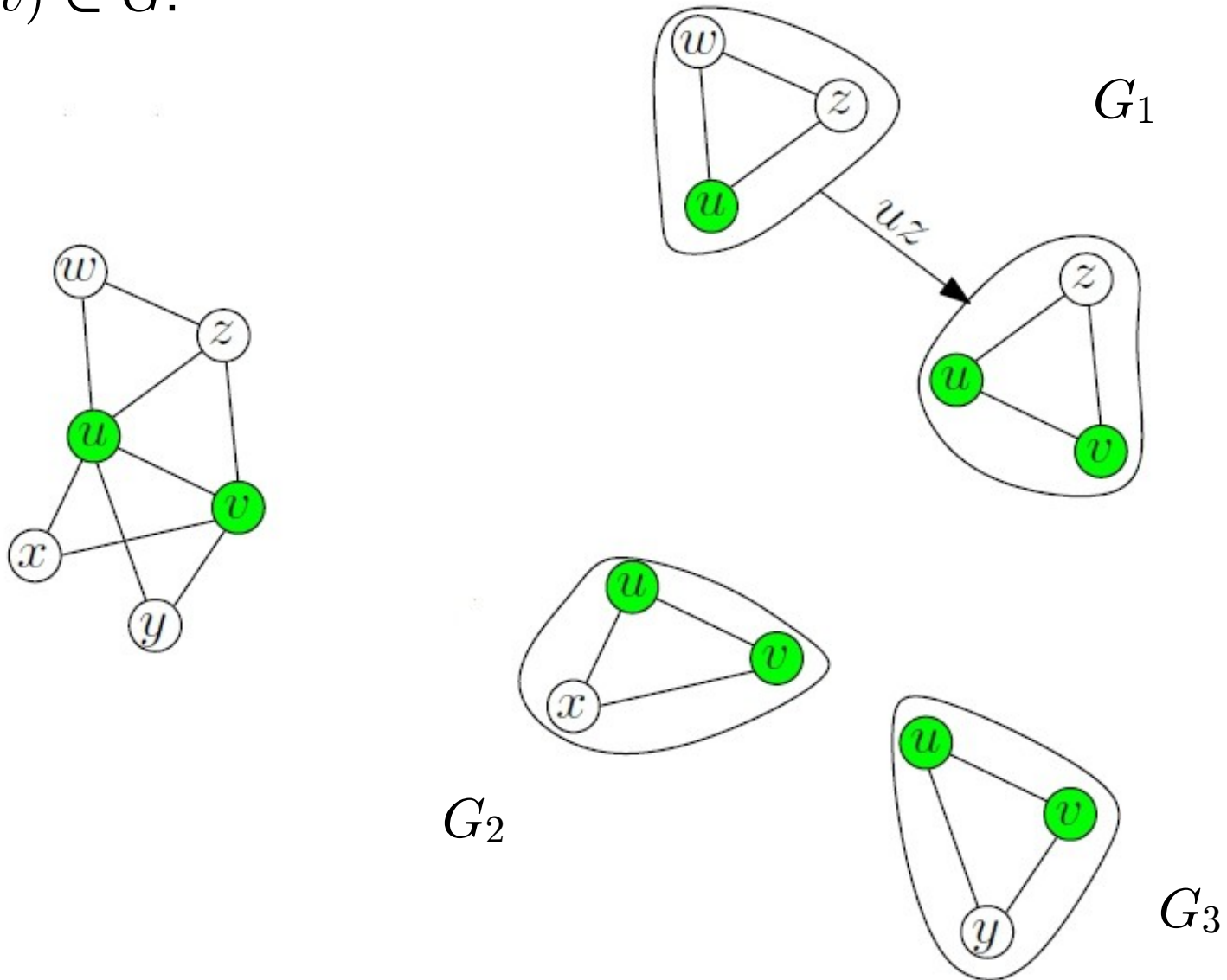
# Decomposition

If  $(u,v) \in G$ :



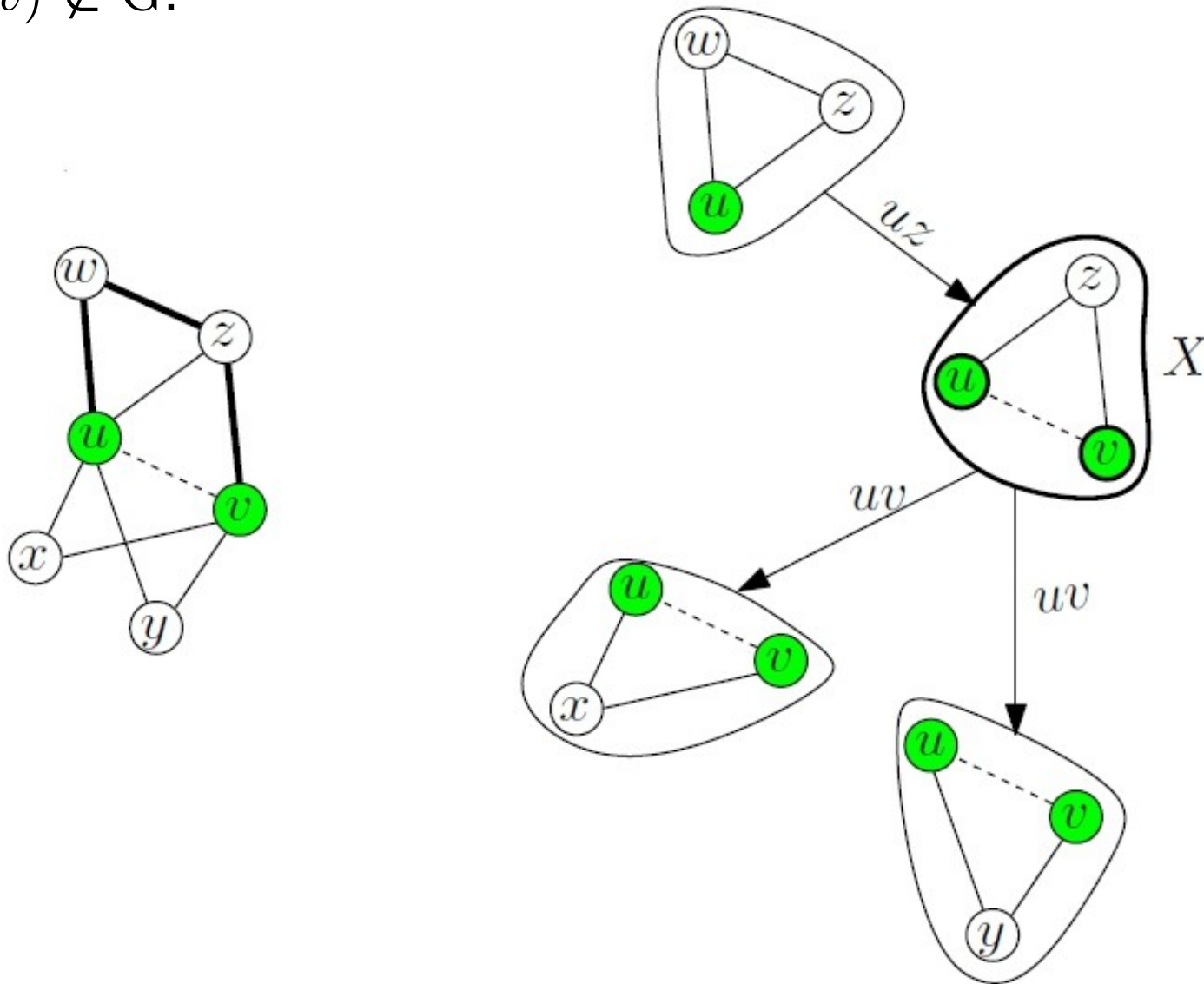
# Decomposition

If  $(u,v) \in G$ :



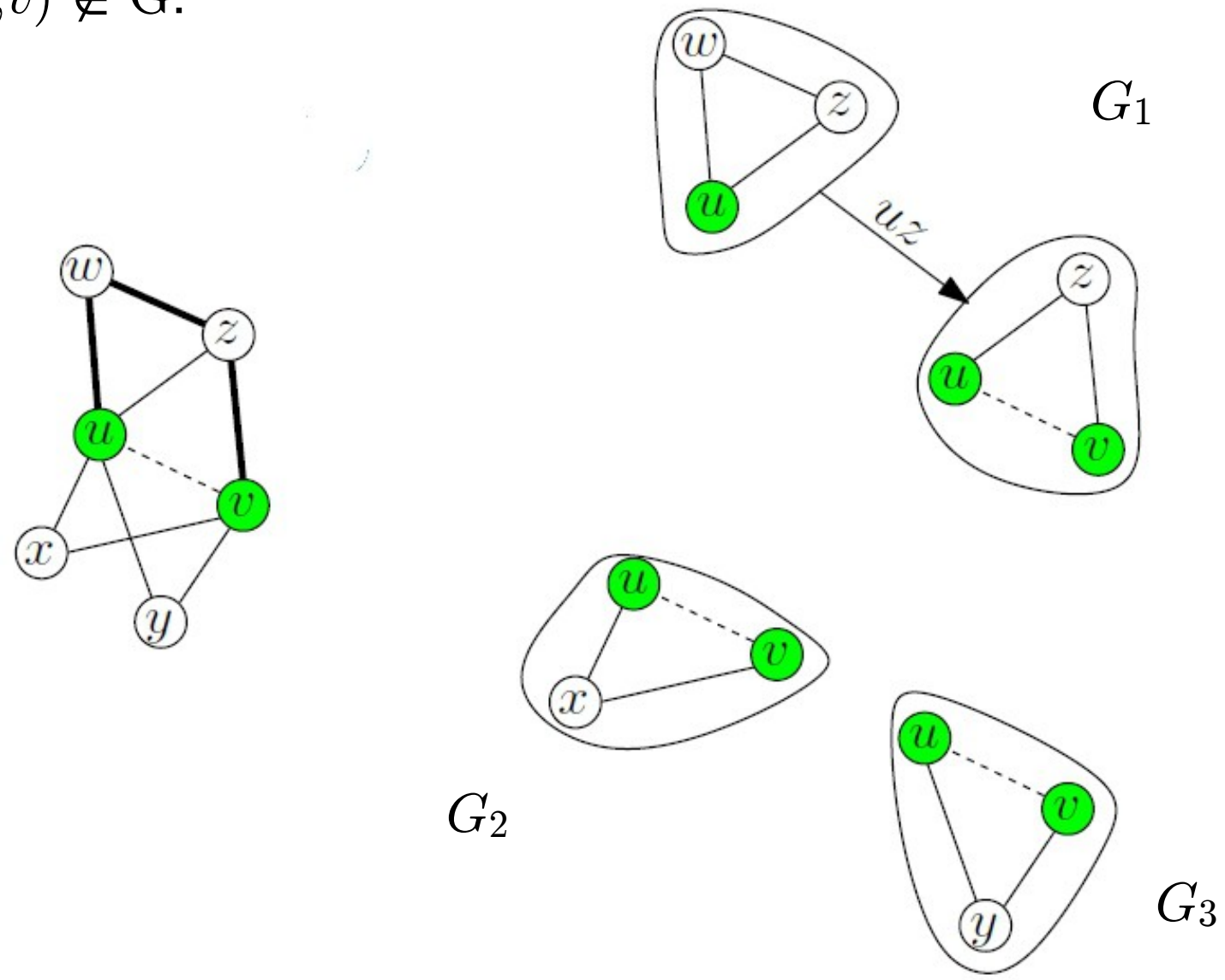
# Decomposition

If  $(u,v) \notin G$ :



# Decomposition

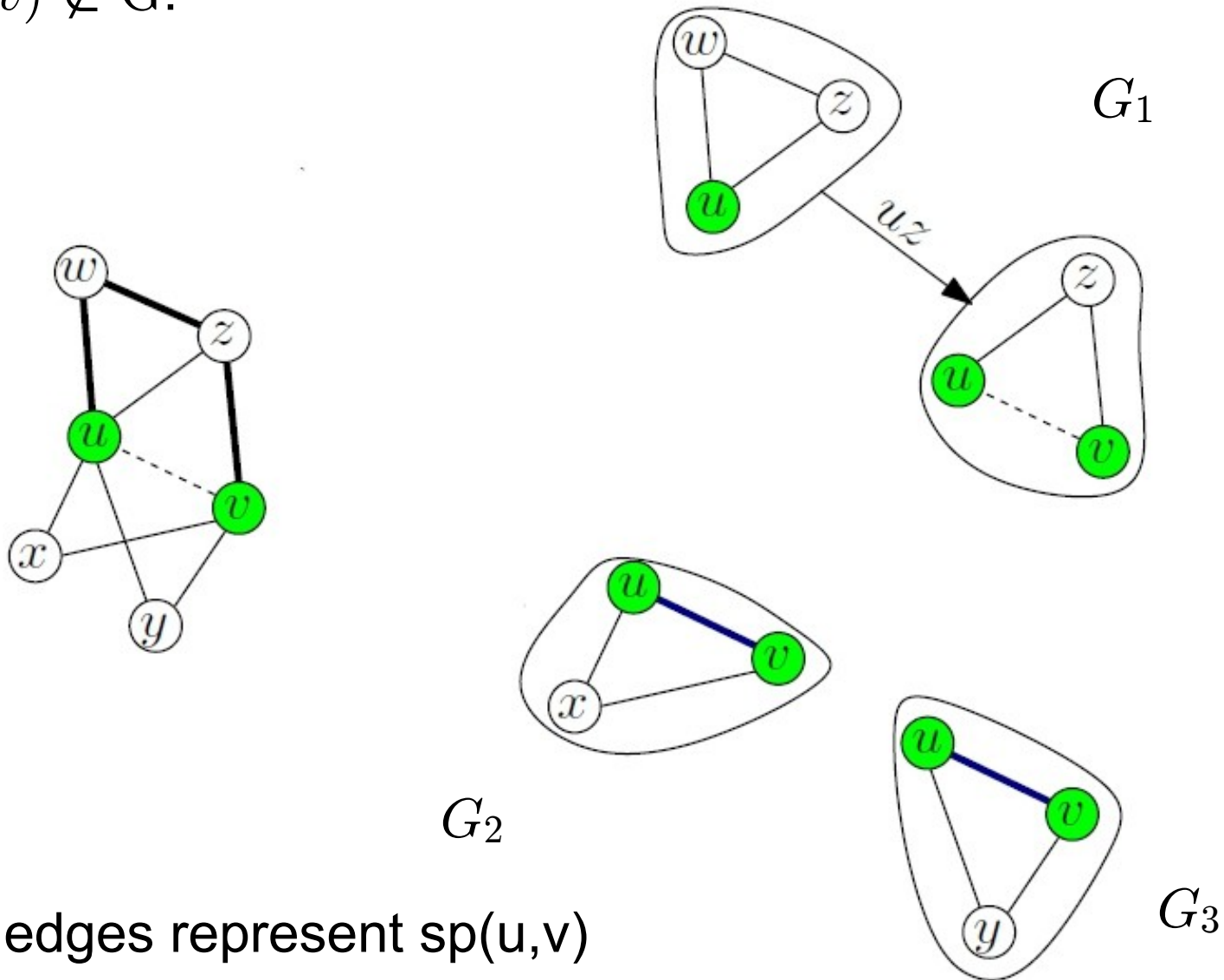
If  $(u,v) \notin G$ :





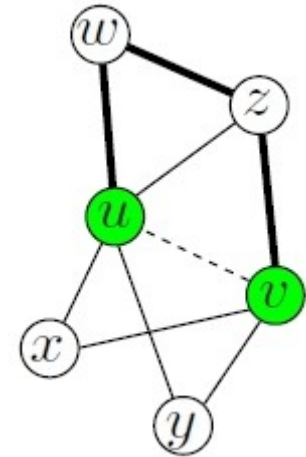
# Decomposition

If  $(u,v) \notin G$ :



# Algorithm

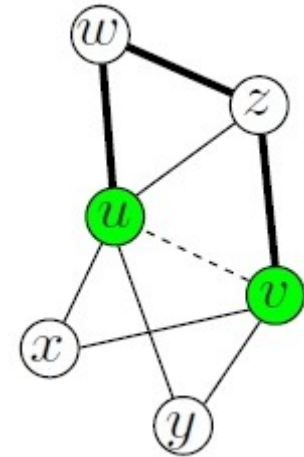
- Find all  $u, v$  such that  $G - u - v$  has at least 3 components



# Algorithm

- Find all  $u, v$  such that  $G - u - v$  has at least 3 components

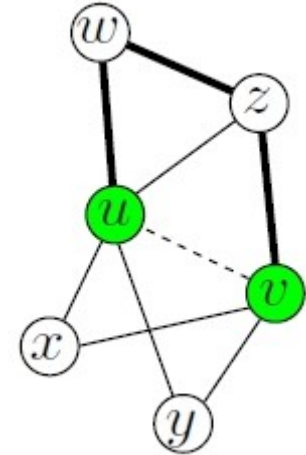
Suitable tree decomposition  
( $u, v$  in common bag)



# Algorithm

- Find all  $u, v$  such that  $G - u - v$  has at least 3 components

Suitable tree decomposition  
( $u, v$  in common bag)

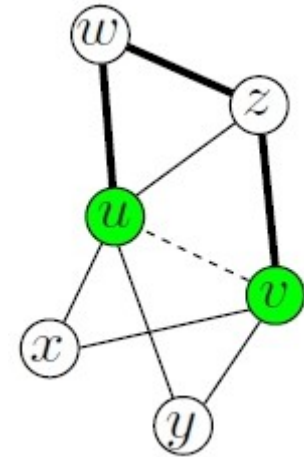


- Find  $G_i$  that contains  $sp(u, v)$  and decompose

# Algorithm

- Find all  $u, v$  such that  $G - u - v$  has at least 3 components

Suitable tree decomposition  
( $u, v$  in common bag)



- Find  $G_i$  that contains  $sp(u, v)$  and decompose

[Chaudhuri-Zaroliagis '00]

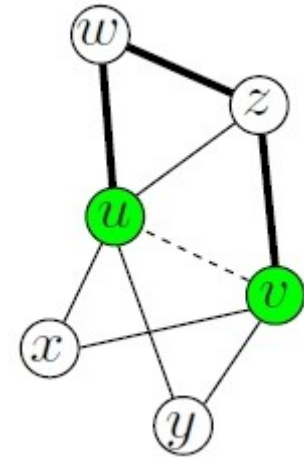
Data structure for fixed tree-width graphs supporting

- intermediate vertex queries in  $O(1)$
- bag location queries in  $O(1)$
- distance queries in  $O(1)$

# Algorithm

- Find all  $u, v$  such that  $G - u - v$  has at least 3 components

Suitable tree decomposition  
( $u, v$  in common bag)



- Find  $G_i$  that contains  $sp(u, v)$  and decompose

[Chaudhuri-Zaroliagis '00]

Data structure for fixed tree-width graphs supporting

- intermediate vertex queries in  $O(1)$
- bag location queries in  $O(1)$
- distance queries in  $O(1)$

- Compute MCB from  $SC(G_i)$  and the SC from loose edges

Thank you!